TERM STRUCTURES OF CREDIT SPREADS WITH INCOMPLETE ACCOUNTING INFORMATION

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We study the implications of imperfect information for term structures of credit spreads on corporate bonds. We suppose that bond investors cannot observe the issuer’s assets directly, and receive instead only periodic and imperfect accounting reports. For a setting in which the assets of the firm are a geometric Brownian motion until informed equityholders optimally liquidate, we derive the conditional distribution of the assets, given accounting data and survivorship. Contrary to the perfect-information case, there exists a default-arrival intensity process. That intensity is calculated in terms of the conditional distribution of assets. Credit yield spreads are characterized in terms of accounting information. Generalizations are provided.

KEYWORDS: Credit risk, corporate bond yields, incomplete information, default intensity.

1. INTRODUCTION

This paper analyses term structures of credit risk and yield spreads in secondary markets for the corporate debt of firms that are not perfectly transparent to bond investors.

The valuation of risky debt is central to theoretical and empirical work in corporate finance. A leading paradigm in corporate-bond valuation has taken as given the dynamics of the assets of the issuing firm, and priced corporate bonds as contingent claims on the assets, as in Black and Scholes (1973) and Merton (1974). Generalizations treat coupon bonds and the effects of bond indenture provisions (Black and Cox (1976) and Geske (1977)) and stochastic interest rates (Shimko, Tejima, and van Deventer (1993) and Longstaff and Schwartz (1995)). By introducing bankruptcy costs and tax effects, this framework has been extended to treat endogenous capital structure, liquidation policy, recapitalization, and renegotiation of debt (Brennan and Schwartz (1984), Fischer, Heinkel, and Zechner (1989), Leland (1994, 1998), Leland and Toft (1996), Uhrig-Homburg (1998), Anderson and Sundaresan (1996), Mella-Baral and Perraudin

We are exceptionally grateful to Michael Harrison for his significant contributions to this paper, which are noted within. We are also grateful for insightful research assistance from Nicolae Gârleanu, Mark Garmaise, and Jun Liu; for very helpful discussions with Martin Jacobsen, Marliese Uhrig-Homburg, Marc Yor, and Josef Zechner; and for comments from Michael Roberts, Klaus Toft, William Perraudin, Monique Jeanblanc, Jean Jacod, Philip Protter, Alain Sznitmann, Emmanuel Gobet, Anthony Neuberger, Jason Wei, Pierre de la Noue, Olivier Scaillet, numerous seminar participants, as well as an editor and several anonymous referees. Duffie was supported in part by the Financial Research Initiative and the Gifford Fong Associates Fund at The Graduate School of Business, Stanford University. We are also grateful for hospitality from the Institut de Finance, Université de Paris, Dauphine, and the Financial Markets Group of the London School of Economics. Lando was supported in part by The Danish Natural and Social Science Research Councils.

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These second-generation models allow for endogenous default, optimally triggered by equity owners when assets fall to a sufficiently low level.

In practice, it is typically difficult for investors in the secondary market for corporate bonds to observe a firm’s assets directly, because of noisy or delayed accounting reports, or barriers to monitoring by other means. Investors must instead draw inference from the available accounting data and from other publicly available information, for example business-cycle data, that would bear on the issuer’s credit quality. Under informational assumptions, we derive public investors’ conditional distribution of the issuer’s assets, explicitly accounting for the implications of imperfect information and survivorship. This provides a model for conditional default probabilities at each future maturity. Default occurs at an arrival intensity that bond investors can calculate in terms of observable variables.

We show several significant implications of incomplete information for the level and shape of the term structure of secondary-market yield spreads (the excess over risk-free interest rates at which corporate bond prices are quoted in public markets). With perfect information, yield spreads for surviving firms are zero at zero maturity, and are relatively small for small maturities, regardless of the riskiness of the firm. As illustrated in Figure 1, yield spreads for relatively risky firms would, with perfect information, eventually climb rapidly with maturity. (The assumptions and parameters used for this figure are explained in Section 2.) Such severe variation in the shape of the term structure of yield spreads is uncommon in practice (Fons (1994), Helwege and Turner (1999), Johnson (1967), Jones, Mason, and Rosenfeld (1984), and Sarig and Warga (1989)). With imperfect information, however, yield spreads are strictly positive at zero maturity because investors’ are uncertain about the nearness of current assets to the trigger level at which the firm would declare default. This uncertainty causes a more moderate variation in spreads with maturity, as illustrated in Figure 1 for an otherwise identical firm whose accounting reports are noisy. The shape of the term structure of credit spreads may indeed play a useful empirical role in estimating the degree of transparency of a firm as viewed by bond-market participants. The existence of a default intensity, moreover, is consistent with the fact that bond prices often drop precipitously at or around the time of default. (With perfect information, as default approaches bond prices would converge continuously to their default-contingent values.)

As opposed to the structural models described above, which link default explicitly to the first time that assets fall below a certain level, a more recent literature has adopted a reduced-form approach, assuming that the default arrival intensity exists, and formulating it directly as a function of latent state variables or predictors of default. The popularity of this reduced-form approach to modeling defaultable bonds and credit derivatives, particularly

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This approach allows the application of statistical methods for estimating the incidence of default (Altman (1968), Bijnen and Wijn (1994), Lennox (1999), Lundstedt and Hillegeist (1998), McDonald and Van de Gucht (1999), Shumway (2001), and the use of convenient methods for risk management and derivative pricing that were originally developed for default-free term structures. We present here a first example of a structural model that is consistent with such a reduced-form representation.

Bounding short spreads away from zero can also be obtained in a structural model in which the assets of a firm are perfectly observable and given by a jump-diffusion process, as in Zhou (1997). This approach is not, however, consistent\(^3\) with a stochastic intensity for default (unless the only variation in

\(^3\)For a stopping time \(\tau\) to have an associated intensity, it must (among other properties) be totally inaccessible, meaning that, for any sequence of stopping times, the probability that the sequence approaches \(\tau\) strictly from below is zero. See, for example, Meyer (1966, p. 130, Definition D42). The first time \(\tau = \inf(V_t \leq V_{\delta})\) that the asset process \(V\) defined by Zhou (1997) crosses the default boundary \(V_\delta\) could be the time of a jump, or could be via a continuous ("diffusion") crossing. That is, if we let \(\tau_n = \inf(t : V_t \leq V_\delta + n^{-1})\), then there is a strictly positive probability that \(\tau_n\) converges to \(\tau\), so \(\tau\) is not totally inaccessible, and therefore does not have an intensity.
asset levels is through jumps). Hence, this approach does not lay the theoretical groundwork for hazard-rate based estimation of default intensities. With precisely measured assets, moreover, this jump-diffusion model offers no role in the estimation of default risk for such potentially useful explanatory variables as duration of survivorship, industrial performance, or consumer confidence. One could, of course, build a model for a firm with complete information in which various different state variables determine the dynamics of assets or liabilities, and would therefore also be determinants of default risk.

2. THE BASIC MODEL

This section presents our basic model of a firm with incomplete secondary-market information about the credit quality of its debt. For simplicity, we treat a time-homogeneous setting, staying within the tradition of the work of Anderson, Pan, and Sundaresan (1995), Anderson and Sundaresan (1996), Fan and Sundaresan (2000), Fischer, Heinkel, and Zechner (1989), Leland (1994, 1998), Leland and Toft (1996), Mella-Barral (1999), Mella-Barral and Perraudin (1997), and Uhrig-Homburg (1998). We solve for the optimal capital structure and default policy, and then derive the conditional distribution of the firm's assets, given incomplete accounting information, along with the associated default probabilities, default arrival intensity, and credit spreads. In Section 3, we treat extensions of the basic model.

2.1. Setup and Optimal Liquidation

We begin by reviewing a standard model of a firm’s assets, capital structure, and optimal liquidation policy. With some exceptions, the results are basically those of Leland and Toft (1996).

The stochastic process \( V \) describing the stock of assets of our given firm is modeled as a geometric Brownian motion, which is defined, along with all other random variables, on a fixed probability space \((\Omega, \mathcal{F}, P)\). In particular, \( V_t = e^{Z(t)} \), where \( Z_t = Z_0 + mt + \sigma W_t \), for a standard Brownian motion \( W \), a volatility parameter \( \sigma > 0 \), and a parameter \( m \in (-\infty, \infty) \) that determines the expected asset growth rate \( \mu = t^{-1} \log E(V_t/V_0) = m + \sigma^2/2 \). The firm generates cash flow at the rate \( \delta V_t \) at time \( t \), for some constant \( \delta \in (0, \infty) \).

The firm issues debt so as to take advantage of the tax shields offered for interest expense, at the constant tax rate \( \theta \in (0, 1) \). In order to stay in a simple time-homogeneous setting, the debt is modeled as a consol bond, meaning a commitment to pay coupons indefinitely at some constant total coupon rate \( C > 0 \). Tax benefits for this bond are therefore received at the constant rate \( \theta C \), until liquidation. (We briefly consider callable debt in Section 3.)

All agents in our model are risk-neutral, and discount cash flows at a fixed market interest rate \( r \).

The debt is sold at time 0 for some amount \( D \) to be determined shortly. For contractual purposes, it is assumed that the debt is issued at par, determining its
face value \( D \) and coupon rate \( C/D \). The optimal amount of debt to be issued will be discussed after considering its valuation.

The firm is operated by its equity owners, who are completely informed at all times of the firm’s assets. This means that they have the information filtration \((\mathcal{F}_t)\) generated\(^4\) by \( V_t \). The expected present value at time \( t \) of the cash flows to be generated by the assets, excluding the effects of liquidation losses and tax shields, conditional on the current level \( V_t \) of assets, is

\[
E \left[ \int_t^\infty e^{-r(t-s)} \delta V_s \, ds \mid V_t \right] = \frac{\delta V_t}{r - \mu},
\]

provided that \( r > \mu \). (If \( \mu \geq r \), the present value of cash flows is infinite, a case we do not consider.) One could therefore equally well take this value or the firm’s cash flow rate \( \delta V_t \), as the state variable for the firm’s opportunities, as these alternative state variables are simply multiples of the stock of assets \( V_t \).

For simplicity, the equity owners’ only choice is when to liquidate the firm. A liquidation policy is an \((\mathcal{F}_t)\)-stopping time \( \tau : \Omega \rightarrow [0, \infty] \). Given an asset level at liquidation of \( V_\tau \), we choose for simplicity to define the liquidation value of the assets to be \( \delta(r - \mu)^{-1}V_\tau \), i.e., the present unlevered value defined in (1). Alternatively, one could consider a liquidation value that reflects the value of assets in an optimally levered, reorganized firm. This would require the solution of an associated fixed-point problem—a problem that is not central to the objectives of this paper. At the chosen liquidation time \( \tau \), a fraction \( \alpha \in [0, 1] \) of the assets are lost as a frictional cost. The value of the remaining assets, \( \delta(r - \mu)^{-1}(1 - \alpha)V_\tau \), is, by an assumption of strict priority, assigned to debt-holders.\(^5\)

Proceeds from the sale of debt are paid at time 0 as a cash distribution to initial equity holders. After this distribution, the initial value of equity to shareholders, given a liquidation policy \( \tau \) and coupon rate \( C \), is

\[
F(V_0, C, \tau) = E \left[ \int_0^\tau e^{-r(t-s)} (\delta V_s + (\theta - 1)C) \, dt \right].
\]

Equity shareholders would therefore choose the liquidation policy solving the optimization problem

\[
S_0 = \sup_{\tau \in \mathcal{F}} F(V_0, C, \tau),
\]

where \( \mathcal{F} \) is the set of \((\mathcal{F}_t)\)-stopping times.

\(^4\) That is, for each \( t > 0 \), \( \mathcal{F}_t \) is the \( \sigma \)-algebra generated by \( \{V_s : 0 \leq s \leq t\} \).

\(^5\) For an alternative formulation, one might suppose that equity holders would receive at liquidation any excess of the recovery value of assets, \( \delta(r - \mu)^{-1}(1 - \alpha)V_\tau \), over the face value \( D \) of debt, with \( \min(\delta(r - \mu)^{-1}(1 - \alpha)V_\tau, D) \) going to debtholders. For certain parameters, such as those used in our illustrative numerical example to follow, the two formulations imply the same default policy and valuations, as equity holders would in any case optimally declare default only when there are insufficient post-recovery assets to cover the face value of debt. In other parameters cases (with large \( V_0 \), \( r \), and \( C \), and with negligible \( \sigma \), \( \mu \), and \( \delta \)), equity holders given the chance for recovery of \( \max(0, \delta(r - \mu)^{-1}(1 - \alpha)V_\tau - D) \) would liquidate at time 0.
If at some time \( t \) the asset level \( V_t \) is less than \( C/\pi \), then equity owners have a net negative dividend rate.\(^6\) Equity owners may nevertheless prefer to continue operating the firm, suffering such negative distributions, bearing in mind that assets might eventually rise and create large future dividends. At some sufficiently low level of assets, however, the prospects for such a future recovery are dim enough to warrant immediate liquidation. Indeed, the optimal liquidation time, as shown in a different context by Leland (1994), is the first time \( \tau(V_B) = \inf(t: V_t \leq V_B) \) that the asset level falls to some sufficiently low boundary \( V_B > 0 \). The optimality of such a trigger policy is unsurprising, as \( V_t \) is a sufficient statistic for the firm’s future cash flows, and cash flows are increasing in \( V_t \).

Specifically, one conjectures that the optimal equity value at time \( t \),

\[
S_t = \text{ess sup}_{\tau \in \mathcal{F}} E \left[ \int_t^\tau e^{-r(t-s)} (\delta V_s + (\theta - 1)C) \, ds \middle| \mathcal{F}_t \right],
\]

is given by \( S_t = w(V_t) \), where \( w \) solves the Hamilton-Jacobi-Bellman differential equation

\[
w''(v) \mu v + \frac{1}{2} w''(v) \sigma^2 v^2 - rw(v) = (1 - \theta)C - \delta v, \quad v > V_B,
\]

with the boundary conditions

\[
w(v) = 0, \quad v \leq V_B,
\]

and

\[
w'(V_B) = 0.
\]

Under this conjecture, to be verified shortly, (6) means that it is no longer optimal to operate the firm once the equity value has been reduced to its liquidation value, while (7) is the so-called “smooth-pasting” condition. The differential equation (5) states that, so long as it is optimal to continue operating the firm, the expected rate of increase in equity value, net of the rate of opportunity cost \( rw(v) \) of equity capital, is equal to the net rate at which cash is paid out by equity.

The HJB equation is solved by \( w(v) = 0 \) for \( v \leq V_B = v_B(C) \), where

\[
v_B(C) = \frac{(1 - \theta)C \gamma (r - \mu)}{r(1 + \gamma)\delta},
\]

where

\[
\gamma = \frac{m + \sqrt{m^2 + 2r\sigma^2}}{\sigma^2},
\]

\(^6\) In a model restricted to have nonnegative net equity dividends per share, such net negative cash distributions could be funded by dilution, for example through share purchase rights issued to current shareholders at the current valuation.

\(^7\) Leland’s 1994 model has \( \delta = 0 \). With \( \delta = 0 \), the manner in which equity holders extract value is not modeled. The subsequent results of Leland and Toft (1996) and Leland (1998) have \( \delta > 0 \), although the candidate solution was not subjected to verification.
and, for \( v > V_B \),

\[
9. \quad w(v) = \frac{\delta v}{r - \mu} - \frac{v_B(C) \delta}{r - \mu} \left( \frac{v}{v_B(C)} \right)^{-\gamma} + (\theta - 1) \frac{C}{r} \left[ 1 - \left( \frac{v}{v_B(C)} \right)^{-\gamma} \right].
\]

The first term in (9) represents the present value of all future cash flows generated by assets, assuming no liquidation. The second term represents the present value of the cash flows lost to distress or transferred to debtholders at the time of liquidation. The last term represents the costs of all future debt coupon payments, net of tax shields. The key factor \((v/v_B(C))^{-\gamma}\) is the present value at an asset level \( v > v_B(C) \) of receiving one unit of account at the stopping time \( \tau(v_B(C)) \).

The optimality property

\[
10. \quad S_0 = w(V_0) = F(V_0, C, \tau(v_B))
\]
is verified as follows. For each \( t \), let

\[
q_t = e^{-r \tau} w(V_t) + \int_0^t e^{-r \tau} (\delta V_s - (1 - \theta) C) \, ds.
\]

From (5) and Ito’s Formula, and noting that for \( v \leq v_B(C) \) we have both \( w(v) = 0 \) and \( \delta v - (1 - \theta) C \leq 0 \), it follows that \( q \) is a uniformly integrable supermartingale. Thus, for any stopping time \( \tau \), we have \( q_\tau \geq E(q_\tau) \). This implies that, for any stopping time \( \tau \), we have

\[
11. \quad E \left[ \int_0^\tau e^{-r \tau} (\delta V_s - (1 - \theta) C) \, ds \right] \leq w(V_0) - E[e^{-r \tau} w(V_\tau)].
\]

As \( w \) is nonnegative, \( w(V_0) \geq F(V_0, C, \tau) \). For the candidate optimal policy \( \tau = \tau(V_B) \), we have \( w(V_\tau) = 0 \) and equality in (11), confirming optimality and (10).

The associated expected present value of the cash flows to the bond at any time \( t \) before liquidation, conditional on \( V_t \), is \( d(V_t, C) \), where

\[
12. \quad d(v, C) = \frac{(1 - \alpha) v_B(C) \delta}{r - \mu} \left( \frac{v}{v_B(C)} \right)^{-\gamma} + \frac{C}{r} \left[ 1 - \left( \frac{v}{v_B(C)} \right)^{-\gamma} \right].
\]

We summarize as follows:

**Proposition 2.1:** Suppose \( r > \mu \). Let \( v_B(C) \) and \( d(V_0, C) \) be defined by (8) and (12), respectively. Then the optimal liquidation problem (3) is solved by the first

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8 Although \( w \) need not be twice continuously differentiable, it is convex, \( C^1 \), and \( C^2 \) except at \( V_B \), where \( w'(V_B) = 0 \). We have \( w(v) = 0 \) for \( v \leq V_B \). Under these conditions,

\[
w(V_t) = w(V_0) + \int_0^t \mathbb{1}_{|V_s| > V_B} \left[ w'(V_t) \mu V_s + \frac{1}{2} w''(V_t) \sigma^2 V_s^2 \right] \, dt + \int_0^t w'(V_t) \sigma V_s \, dB_s.
\]

(See, for example, Karatzas and Shreve (1998, page 219).) Because \( w'(v) \) is bounded, the last term is a martingale.
time $\tau(v_B(C))$ that $V$ is at or below $v_B(C)$. The associated initial values of equity and debt are $w(V_0)$ and $d(V_0, C)$, respectively, where $w$ is given by (9) for $v > v_B(C)$ and $w(v) = 0$ for $v \leq v_B(C)$.

We suppose that the total coupon rate $C^*(V_0)$ of the bonds to be issued is chosen so as to maximize over $C$ the total initial firm valuation, $F(V_0, C, \tau(v_B(C)) + d(V_0, C)$, which is the initial value of equity plus the sale value of debt.

2.1.1. Example: Optimal Capital Structure and Liquidation

As a numerical illustration, we consider the case

$$\theta = 0.35; \quad \sigma = 0.05; \quad r = 0.06; \quad m = 0.01; \quad \delta = 0.05; \quad \alpha = 0.3.$$  

As the solutions for the optimal total coupon rate $C^*(V_0)$ and the optimal liquidation boundary $V_B = v_B(C^*(V_0))$ are linear in $V_0$, we may without loss of generality take $V_0 = 100$. For these parameters, we have the optimal total coupon rate $C = 8.00$, liquidation boundary $V_B = v_B(C) = 78.0$, and initial par debt level $D = d(V_0, C) = 129.4$.

The yield of the debt is $C/D = 6.18\%$. Recovery of the debt at default, as a fraction of face value, is $\delta(r - \mu)^{-1}(1 - \alpha)V_B/D = 43.3\%$. For comparison, the average recovery, as a fraction of face value, of all defaulted bonds monitored\(^9\) by the rating agency Moody’s, for 1920 to 1997, is 41%. Of course, recovery varies by subordination and for other reasons.

2.2. Imperfect Bond Market Information

Now we turn to how the secondary-market assesses the firm’s credit risk and values its bonds.

After issuance, bond investors are not kept fully informed of the status of the firm. While they do understand that optimizing equity owners will force liquidation when assets fall to $V_B$, bond investors cannot observe the asset process $V$ directly. Instead, they receive imperfect information at selected times $t_1, t_2, \ldots$, with $t_i < t_{i+1}$. While extensions to more general observation schemes are provided in the next section, for now we assume that at each observation time $t$ there is a noisy accounting report of assets, given by $\hat{V}_t$, where $\log \hat{V}_t$ and $\log \hat{V}_i$ are joint normal. Specifically, we suppose that $Y(t) = \log \hat{V}_t = Z(t) + U(t)$, where $U(t)$ is normally distributed and independent of $Z(t)$. (The independence assumption is without loss of generality, given joint normality.)

Also observed at each $t \in [0, \infty)$ is whether the equity owners have liquidated the firm. That is, the information filtration $(\mathcal{F}_t)$ available to the secondary

market is defined by

\[
\mathcal{H}_t = \sigma\{Y(t_1), \ldots, Y(t_n), 1_{[t \leq s]} : 0 \leq s \leq t\},
\]

for the largest \( n \) such that \( t_n \leq t \), where \( \tau = \tau(V_0) \).

For simplicity, we suppose that equity is not traded on the public market, and that equity owner-managers are precluded, say by insider-trading regulation, from trading in public debt markets. This allows us to maintain the simple model (\( \mathcal{H}_t \)) for the information reaching the secondary bond market, and avoiding a complex rational-expectations equilibrium problem with asymmetric information.

Our main objective for the remainder of this subsection is to compute the conditional distribution of \( V_t \) given \( \mathcal{H}_t \). We will begin with the simple case of \( t \) having observed a single noisy observation at time \( t \). In Section 3, we extend\(^{10}\) to multiple observation times.

We will need, as an intermediate calculation, the probability \( \psi(z, x, t) \) conditional on \( Z_t \) starting at some given level \( z \) at time 0 and ending \( x \) at a given time \( t \), that \( \min(Z_s : 0 \leq s \leq t) > 0 \). As indicated by our notation, this probability does not depend on the drift parameter \( m \), and depends on the variance parameter \( \sigma_t^2 \) and time \( t \) only through the term \( k = \sigma_t^2 \). From the density of the first-passage time recorded in Chapter 1 of Harrison (1985), and from Bayes' Rule, one obtains after some simplification that

\[
\psi(z, x, k) = 1 - \exp\left(-\frac{2zx}{k}\right).
\]

Next, fixing \( z_0 = Z_0 \), we calculate the density \( b(Y_t, z_0, t) \) of \( Z_t \), “killed” at \( \tau = \inf(t : Z_t \leq \underline{u}) \), conditional on the observation \( Y_t = Z_t + U_t \). That is, using the conventional informal notation,

\[
b(x|Y_t, z_0, t) dx = P(\tau > t \text{ and } Z_t \in dx|Y_t), \quad x \geq \underline{u}.
\]

Using the definition of \( \psi \) and Bayes' Rule,

\[
b(x|Y_t, z_0, t) = \frac{\psi(z_0 - \underline{u}, x - \underline{u}, \sigma_t^2) \phi_U(Y_t - x) \phi_Y(x)}{\phi_Y(Y_t)},
\]

where \( \phi_U \) denotes the density of \( U_t \), and likewise for \( \phi_Z \) and \( \phi_Y \). These densities are normal, with respective means \( \bar{u} = E(U_t) \), \( mt + z_0 \), and \( mt + z_0 + \bar{u} \), and with respective variances \( a^2 = \text{var}(U_t) \), \( \sigma_t^2 t \), and \( a^2 + \sigma_t^2 t \). The standard

\(^{10}\) The approach taken here, as well as the specific calculations for a slightly different case, were generously shown to us by Michael Harrison. We are much in his debt for this assistance.

\(^{11}\) To be more precise, if we take \( Z \) to be a pinned standard Brownian motion, with \( Z_0 = z > 0 \) and \( Z_t - x > 0 \), we want the probability \( \psi(z, x, t) \) that \( \min(Z_s : 0 \leq s \leq t) > 0 \).
deviation $a$ of $U_t$ may be thought of as a measure of the degree of accounting noise.

We have

$$P(\tau > t | Y_t) = \int_{-\infty}^{+\infty} b(z | Y_t, z_0, t) \, dz.$$  

(18)

Finally, we compute the density $g(\cdot | Y_t, z_0, t)$ of $Z_t$, conditional on the noisy observation $Y_t$ and on $\tau > t$. Using (16) and (18), and another application of Bayes’ Rule,

$$g(x | y, z_0, t) = \frac{b(x | y, z_0, t)}{\int_{-\infty}^{+\infty} b(x | y, z_0, t) \, dz}.$$  

(19)

Letting $\hat{y} = y - v - \bar{u}$, $\hat{x} = x - v$, and $\hat{z} = z_0 - v$, a calculation of the integral in (19) leaves us with

$$g(x | y, z_0, t) = \frac{\sqrt{\beta_0}}{\pi} e^{-J(\hat{y}, \hat{x}, \hat{z})} \left[ 1 - \exp\left( \frac{-2\hat{z}_0 \hat{x}}{\sigma^2 t} \right) \right] \exp\left( \frac{\beta_1^2 - \beta_3}{4\beta_0} \right) \Phi\left( \frac{\beta_1}{\sqrt{2\beta_0}} \right) - \exp\left( \frac{\beta_2^2 - \beta_3}{4\beta_0} \right) \Phi\left( \frac{-\beta_2}{\sqrt{2\beta_0}} \right),$$

where

$$J(\hat{y}, \hat{x}, \hat{z}) = \frac{(\hat{y} - \hat{x})^2}{2a^2} + \frac{(\hat{z}_0 + mt - \hat{x})^2}{2\sigma^2 t},$$  

(20)

for

$$\beta_0 = \frac{a^2 + \sigma^2 t}{2a^2 \sigma^2 t},$$  

(22)

$$\beta_1 = \frac{\hat{y}}{a^2} + \frac{\hat{z}_0 + mt}{\sigma^2 t},$$  

(23)

$$\beta_2 = -\beta_1 + 2\frac{\hat{z}_0}{\sigma^2 t},$$  

(24)

$$\beta_3 = \frac{1}{2} \left( \frac{\hat{y}^2}{a^2} + \frac{(\hat{z}_0 + mt)^2}{\sigma^2 t} \right),$$  

(25)

and where $\Phi$ is the standard-normal cumulative distribution function. Given survival to $t$, this gives us the conditional distribution of assets, because the conditional density of $V_t$ at some level $v$ is easily obtained from the conditional density of $Z_t$ at log $v$. 

2.2.1. Numerical Illustration—Continued

We extend the numerical illustration begun in Section 2.1.1 by considering the conditional distribution of assets for the same firm at some current date $t > 1$. We suppose that a noise-free asset report of $\hat{V}(t - 1) = V(t - 1) = 86.3$ was provided one year ago. Figure 2 shows the conditional density of the current asset level $V$, given $\mathcal{F}$, that would be realized in the event that the bond has not yet defaulted ($\tau(V) > t$) and the current asset report $\hat{V}$ has an outcome equal to the previous year’s report, 86.3. As the default boundary is $V = 78$, the firm has become rather risky in this scenario. We indicate various cases for the standard deviation $a$ of the accounting noise $U$. Our basic case is $a = 10\%$. We have no empirical evidence at this writing of a reasonable level of accounting noise, which in any case would presumably vary with the nature of a firm, so we consider the effect of variation in $a$. We suppose in all cases that $U$ has expectation $\mu = -a^2/2$, so that $E(e^{U(t)}) = 1$, implying an unbiased accounting report. Figure 3 shows how this conditional density is affected by the lagged asset report $\hat{V}(t - 1)$, for all other parameters at their base cases.

\[ \text{Figure 2.—Conditional density for varying accounting precision.} \]

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12 This does not imply that the accounting report is conditionally unbiased given survivorship. One may think, for example, of an accounting report based on a physical measurement of the stock of assets, which is imperfect but unbiased. An alternative would be an accounting report in the form of a conditional distribution of assets, given survivorship and the results of noisy measurements. The mean of this conditional distribution would, by definition, be conditionally unbiased.
We also compute the $\mathcal{F}_t$-conditional probability $p(t,s)$ of survival to some future time $s > t$. That is, $p(t,s) = P(\tau > s | \mathcal{F}_t)$. For $t < \tau$, we have

\begin{equation}
    p(t,s) = \int_{-\infty}^{\infty} (1 - \pi(s-t, x-v)) g(x | Y_t, z_0, t) \, dx,
\end{equation}

where $\pi(t,x)$ denotes the probability of first passage of a Brownian motion with drift $m$ and volatility parameter $\sigma$ from an initial condition $x > 0$ to a level below 0 before time $t$, which is known explicitly (Harrison (1985)). Figure 4 illustrates outcomes of the conditional default probability $1 - p(t,s)$, for our base-case example, for various time horizons $s-t$ and various levels $a$ of accounting noise. For example, with perfect information, the conditional probability of default within one year is approximately 2.9%, while this conditional probability is approximately 6.7% if the accounting assets are reported with a 10% level of accounting noise.

2.3. Default Intensity

The conditional probability that default occurs within $h$ units of time goes to zero as $h$ goes to zero, regardless of the informational assumptions. What distinguishes perfect from imperfect information is the rate of convergence. In
the case of perfect information, that is, for a filtration such as \((\mathcal{F})\) to which \(Z\) is adapted, on the event that \(\tau > t\) we have

\[
\lim_{h \downarrow 0} \frac{P(\tau \leq t + h | \mathcal{F})}{h} = \frac{\pi(h, Z_t - \nu)}{h} = 0 \quad \text{a.s.}
\]

In structural models with default defined as the first hitting time of an observable diffusion, it is this fact that forces credit spreads on zero-coupon bonds to go to zero as time to maturity goes to zero, as in Figure 1. It is tempting to conclude that the same is true with imperfect information, because, as we see from (26),

\[
\frac{1 - p(t, t + h)}{h} = \int_{\mathbb{R}} \pi(h, x - \nu) g(x | Y_t, z_0, t) dx,
\]

and the first factor of the integrand converges to 0 for all \(x\). The integral itself, however, does not converge to 0 as \(h\) goes to 0. In this section, we prove that (in general) a nonzero limit exists, we give an explicit expression for the limit, and we show that this limit is in fact the intensity of \(\tau\), defined as follows. The default stopping time \(\tau\) has an intensity process \(\lambda\) with respect to the filtration

**Figure 4.**—Default probability, varying accounting precision.
(\(\mathcal{F}\)) if \(\lambda\) is a nonnegative progressively measurable process satisfying \(\int_0^t \lambda_s \, ds < \infty\) a.s. for all \(t\), such that \(\{1_{[r \leq t]} - \int_0^t \lambda_s \, ds : t \geq 0\}\) is an \((\mathcal{F}_t)\)-martingale. For details, see, for example, Brémaud (1981).

The intuitive meaning of the intensity is that it gives a local default rate, in that
\[
P(\tau \in (t, t + dt) | \mathcal{F}_t) = \lambda_t \, dt.
\]

From the results in Section 2.2, at any \((\omega, t)\) such that \(0 < t < \tau(\omega)\), the \(\mathcal{F}_t\)-conditional distribution of \(Z_t\) has a continuously differentiable conditional density \(f(t, \cdot, \omega)\). This density is zero at the boundary \(\underline{\tau}\), and has a derivative (from the right) \(f_+(t, \underline{\tau}, \omega)\) that exists and is nonzero. We are ready to state the key result of this section.

**Proposition 2.2:** Define a process \(\lambda\) by \(\lambda(t) = 0\) for \(t > \tau\) and
\[
\lambda_t(\omega) = \frac{1}{2} \sigma^2 f_+(t, \underline{\tau}, \omega), \quad 0 < t \leq \tau.
\]

Then \(\lambda\) is an\(^{13}\) \((\mathcal{F}_t)\)-intensity process of \(\tau\).

A proof is found in Appendix A. In order to gain intuition for the result, we consider a standard binomial “random-walk” approximation for \(Z\), supposing at first that \(m = 0\). We can assume without loss of generality that the default-triggering boundary \(\underline{\tau}\) for \(Z\) is 0. For notational simplicity, we let \(f(\cdot)\) also denote the \(\mathcal{F}_t\)-conditional density of \(Z_t\) on the event that \(\tau > t\). The conditional probability that \(Z_t = 0\) is zero. The conditional probability that \(Z_t\) is one step above 0 is, to first order, approximated by \(f(\sigma \sqrt{h}) \sigma \sqrt{h}\), as illustrated in Figure 5.

![Figure 5](image-url)

**Figure 5.**—Binomial approximation of hitting intensity.

\(^{13}\) While there may exist other \((\mathcal{F}_t)\)-intensity processes for \(\tau\), they are equivalent for our purposes. For the sense in which uniqueness applies, see Brémaud (1981, p. 30).
Because the only level from which \( Z_t \) can reach 0 within one time step of length \( h \) is \( \sigma \sqrt{h} \), the conditional probability of hitting 0 by time \( h \) is equal to \( \frac{1}{2} f(\sigma \sqrt{h}) \sigma \sqrt{h} \). Thus,

\[
\lim_{h \to 0} \frac{1}{h} P(\tau \leq t + h | \mathcal{F}_t) = \lim_{h \to 0} \frac{\frac{1}{2} f(\sigma \sqrt{h}) \sigma \sqrt{h}}{h} = \lim_{h \to 0} \frac{\frac{1}{2} f(\sigma \sqrt{h}) \sigma^2}{\sigma \sqrt{h}} = \frac{1}{2} f'(0) \sigma^2,
\]

where we have used the fact that \( f(0) = 0 \) to calculate the derivative. This binomial approximation can easily be extended to handle a drift term \( m \) by changing the probability of up and down moves to

\[
\frac{1}{2} + \frac{mv \sqrt{h}}{2\sigma} \quad \text{and} \quad \frac{1}{2} - \frac{mv \sqrt{h}}{2\sigma},
\]

respectively. As \( h \) goes to zero these probabilities go to \( \frac{1}{2} \), and we have the same limit result for the intensity.\(^{14}\)

2.4. Credit Spreads

We turn now to the implications of incomplete information for the term structures of credit yield spreads of the modeled firm.

For a given time \( T \) to maturity, the yield spread on a given zero-coupon bond selling at a price \( \varphi > 0 \) is the real number \( \eta \) such that \( \varphi = e^{-rT} \eta \). If we assume that a bond with maturity date \( s > t \) issued by our modeled firm recovers some fraction \( R(s) \in [0,1] \) of its face value at default, then the secondary market price \( \varphi(s,t) \) at time \( t \) of such a bond, in the event that the firm has yet to default by \( t \), is given by

\[
\varphi(t, s) = e^{-r(s-t)} p(t, s) - R(s) \int_t^s e^{-r(u-t)} p(t, du),
\]

where we recall that \( p(t, u) \) is the probability of survival to time \( u \). The first term in (29) is the value of the survival-contingent contractual payoff of the bond at maturity, while the second is the value of any recovery at default, contingent on default before maturity. Using (26), our calculation of \( \varphi(t, s) \) is reduced to a single numerical integration over the current log-asset level \( x \), weighted by its conditional density, applying Fubini's Theorem to the integral in (29). As our model was based for simplicity on a single consol bond, and as our

\(^{14}\) This is a reflection of the fact that, locally, the volatility dominates the evolution of the Brownian motion. This can be seen from the law of the iterated logarithm (for example, Karatzas and Shreve 1988).
calculation of the survival probability \( p(t,s) \) is based on that capital structure, some interpretation of (29) is appropriate. One possibility is that the consol is stripped in the secondary market into a continuum of zero-coupon bonds. While various recovery assumptions could be made, it is convenient for our purposes to assume that, given default at time \( \tau \), the recovery \( R(s) \) for a bond with maturity date \( s > \tau \) is proportional to the default-free discount \( e^{-\tau(s-\tau)} \) for that maturity. (This could, for instance, be a contractual provision.) Later, we consider default swap spreads, which do not call for such recovery assumptions.

Figure 1 compares the term structure of credit spreads in our base-case numerical illustration with the term structure that would apply with perfect accounting data (dashed curve, for the case with \( a = 0 \)). Figure 8 compares the base case (solid curve) with the term structure that would apply with various qualities of accounting information. Figure 9 compares the base case (solid curve) against the term structure that would apply with various lagged asset reports. With perfect accounting information, the previous accounting report would be irrelevant, given the current report. Figures 6 and 7 compare default intensities across cases treated in Figures 8 and 9, respectively.

In a setting of perfect information \( (a = 0) \), we have \( \varphi(t,s) = J_{t,s}(V) \), for \( J_{t,s} : [0, \infty) \to (0, \infty) \) determined by (29). If \( m > 0 \), it can be shown by calculation...
of its second derivative that $J_{t,s}(\cdot)$ is concave.\textsuperscript{15} It follows by Jensen’s Inequality that yield spreads are larger at an outcome for $V_t$ than they would be in the case of perfect information. This is analogous to the fact that, in a Black-Scholes setting, the equity price as a function of asset level is increasing in the volatility of assets, and therefore the debt price is decreasing in asset volatility. Here, however, the asset volatility is fixed, and it is a question of precision of the accounting observation. One might extrapolate to practical settings and anticipate that, other things equal, secondary-market yield spreads are decreasing in the degree of transparency of a firm. We emphasize this as separate from the adverse-selection effect on new-issue prices, which may suffer from a lemon’s premium associated with the issuer’s superior information regarding its own credit quality. In our setting, all participants in the secondary market for bonds are equally well informed; they simply adjust their views regarding credit risk based on the precision of their information.

\textsuperscript{15} A proof, due to Nicolae Gârleanu, is provided in a working-paper version of this paper. If $m < 0$, counterexamples can be constructed.
2.4.1. Default-Swap Spreads

Default swaps are the most common form of credit derivative. With a given maturity $T$, a default swap is an exchange of an annuity stream at a constant coupon rate until maturity or default, whichever is first, in return for a payment of $X$ at default, if default is before $T$, where $X$ is the difference between the face value and the recovery value on the stipulated underlying bond. A default swap can thus be thought of as a default insurance contract for bond holders that expires at a given date $T$, and makes up the difference between face and recovery values in the event of default.

By considering the market valuation of default swaps, we can effectively uncover (as explained below) the term structure of credit spreads for par coupon bonds. This is a measure of credit spreads that is more standard than the zero-coupon bond structure considered above. Moreover, our results regarding the shape of the zero-coupon term structure $\varphi(t, \cdot)$ are sensitive to our assumption regarding how these strips share in the assets remaining after default. Default-swap spreads depend only on the total recovery value to the underlying consol bond.
We assume, as typical in practice, that the default-swap annuity payments are made semiannually, and that the default swap’s maturity date $T$ is a coupon date. We take the underlying bond to be the consol bond issued by the firm in our example. This fixes the default-contingent payment, for each default swap, of

$$X = 1 - \frac{(1 - \alpha) \delta V_B}{(r - \mu) D}.$$

We can solve for the at-market default-swap spread, which is the annualized coupon rate $c(t, T)$ that makes the default swap sell at time $t$ for a market value of 0. With $T = t + n/2$, for a given positive integer $n$, we have

$$c(t, T) = \frac{2XE \left[ e^{-(r-\delta)}I_{(t \leq T)} \right]}{\sum_{i=1}^{n} e^{-0.5r_i}E \left[ I_{(T > t + 0.5i)} \right]}.$$

Default-swap spreads are a standard for price quotation and credit information in bond markets. In our setting, they have the additional virtue of providing implicitly the term structure of credit spreads for par floating-rate bonds of the same credit quality as the underlying consol bond, in terms of default time and

**Figure 9.** Credit spreads, varying previous year’s asset level.
recovery at default. Figure 10 compares default-swap spreads, in our base-case model, with imperfect and perfect information.

2.5. Summary of Empirical Implications

We summarize some of the empirical implications of our model for corporate debt valuation as follows.

Even if default is triggered by an insufficient level of assets relative to liabilities, observable variables that are correlated with current asset-liability ratios have explanatory power for credit spreads and for default probabilities. For example, as with Bijnen and Wijn (1994), Lennox (1999), Lundstedt and Hillegeist (1998), McDonald and Van de Gucht (1999), and Shumway (2001), firm-specific ratios (such as interest expense to income), or macroeconomic variables related to the business cycle, may have predictive power for default probabilities or yield spreads, even after exploiting asset and liability data. (We offer some specific modeling in Section 3.) We have also shown the contributing role of lagged accounting variables.

Perfect observation in standard diffusion models of corporate debt, such as those of Leland (1994) and Longstaff and Schwartz (1995), implies that credit spreads also go to zero as maturity goes to zero, regardless of the credit quality of the issuer. For poorer-quality firms, credit spreads would widen sharply with maturity, and then typically decline. With imperfect information about the firm’s value, however, credit spreads remain bounded away from zero as maturity goes to zero. The shape of the term structure of credit spreads is moderated, and may provide some indication of the quality of accounting information assumed by investors.

A “Jensen effect” implies a lower price of debt, fixing the reported level of assets, for an issuer with a conditionally unbiased but imperfect asset report than for a perfectly observable issuer that is otherwise identical. This follows...
from the fact that, under certain conditions, including examples provided in this paper, corporate bond prices in a setting of perfect information are concave in the issuer’s asset level.

Our model is consistent with the fact that bond or equity prices often drop precipitously at or around the time of default. Empirically, given the imperfect manner in which the “surprise” may be revealed around the time of default, we would expect to see a marked increase in the volatility of bond returns during the time window bracketing default. Some evidence in this direction is already available in Beneish and Press (1995) and Slovin, Sushka, and Waller (1997).19

3. EXTENSIONS

This section outlines some extensions of the basic model. First, we allow for inference regarding the distribution of assets from several variables correlated with asset value, or from more than one period of accounting reports. We briefly discuss how to model recapitalization, or decisions by the firm that may be triggered by more than one state variable, such as a stochastic liquidation

19 Some of the evidence presented in Slovin, Sushka, and Waller (1997) is through the stock price reaction of creditors of the defaulting firm.
boundary. We characterize the default intensity for cases in which the asset process \( V \) is a general diffusion process, with a general observation scheme.

3.1. Conditioning on Several Signals

Suppose, extending from Section 2.2, that the observation \( Y \) made at time \( t \) is valued in \( \mathbb{R}^k \) for some \( k \geq 1 \), and is joint normal with \( Z \). This may accommodate observations, beyond merely noisy observation of assets, that have explanatory power for credit risk and yield spreads, such as various accounting ratios, peer performance measures, or even macroeconomic variables, such as consumer sentiment panel data, stock-market indices, or economic growth-rate measures.

For convenience, we let \( G_{ZY} \) denote the conditional expectation of \( Y \) given \( Z \). That is, \( G_{ZY} : \mathbb{R} \rightarrow \mathbb{R}^k \) is affine, and determined as usual by the means and covariances of \( (Y, Z) \). We note that, by joint normality, if we define \( U \) to be the “residual vector” \( U = Y - G_{ZY} \), then \( U \) is independent of \( Z \). We let \( \phi_{U}(\cdot) \) denote the (joint-normal) density of \( U \), and \( \phi_{Y}(\cdot) \) denote the joint density of \( Y \). Now, \( b \) in (17) is redefined by

\[
(30) \quad b(x|Y_t, z_0, t) = \frac{\psi(z_0 - \mu, x - \mu, \sigma \sqrt{t}) \phi_U(Y_t - G_{ZY}(x)) \phi_Z(x)}{\phi_Y(Y_t)}
\]

and the solution for \( g \) given by (19) continues to apply.

3.2. Conditioning with Several Periods of Reports

We now suppose that noisy reports of assets arrive at successive integer dates. Because it is reasonable to allow for persistence in accounting noise, we suppose that \( U_1, U_2, \ldots \) may be serially correlated. Specifically, we suppose that \( Y_t = Z_t + U_t \), for

\[
(31) \quad U_t = \kappa U_{t-1} + \epsilon_t,
\]

where \( \kappa \) is a fixed coefficient and \( \epsilon_1, \epsilon_2, \ldots \) are independent and identically distributed normal random variables, independent of \( Z \).

Let
- \( z^{(n)} = (z_1, z_2, \ldots, z_n) \) denote an outcome of \( Z^{(n)} = (Z_1, Z_2, \ldots, Z_n) \).
- \( y^{(n)} = (y_1, y_2, \ldots, y_n) \) denote an outcome of \( Y^{(n)} = (Y_1, Y_2, \ldots, Y_n) \).
- \( u^{(n)} = y^{(n)} - z^{(n)} \) denote an outcome of \( U^{(n)} = Y^{(n)} - Z^{(n)} \).

We let \( b_n(\cdot|Y^{(n)}) \) denote the improper conditional density of \( Z^{(n)} \), killed with first exit before time \( n \), given \( Y^{(n)} \). As with (16), this is the density defined by \( P(Z^{(n)} \in dz^{(n)} \text{ and } \tau > n | Y^{(n)}) \). For notational simplicity, at the outcomes \( z^{(n)}, y^{(n)}, \) and \( u^{(n)} \), we let \( p_Y(u_n | u_{n-1}) \) denote the transition density of \( U_1, U_2, \ldots; p_Z(z_n | z_{n-1}) \) denote the transition density of \( Z_1, Z_2, \ldots; \) and \( p_Y(y_n | y^{(n-1)}) \)
denote the conditional density of $Y_n$ given $Y^{(n-1)}$. For the case of $\kappa = 0$ (serially uncorrelated noise), it may be seen that $Y_1, Y_2, \ldots$ is autoregressive of order 1, and $p_Y$ takes a simple form.

By Bayes’ Rule,
\[
b_n(z^{(n)}|y^{(n)}) = \frac{P(\tau > n, Z^{(n)} \in dz^{(n)}, Y^{(n)} \in dy^{(n)})}{P(Y^{(n)} \in dy^{(n)})}.
\]

As the event \(\{\tau > n, Z^{(n)} \in dz^{(n)}, Y^{(n)} \in dy^{(n)}\}\) is the same as the event \(A \cap B\), where \(A = \{\tau > n, Z_n \in dz_n, Y_n \in dy_n\}\) and
\[
B = \{\tau > n - 1, Z^{(n-1)} \in dz^{(n-1)}, Y^{(n-1)} \in dy^{(n-1)}\},
\]
we have
\[
b_n(z^{(n)}|y^{(n)}) = \frac{P(A \cap B)P(Y^{(n-1)} \in dy^{(n-1)})}{P_Y(Y_n|y^{(n-1)})}.
\]

After some straightforward manipulation of this expression, we find that $b_n(z^{(n)}|y^{(n)})$ is given by
\[
\frac{\psi(z_{n-1} - \hat{\gamma}z_n - \hat{\gamma}^n, \sigma) p_Z(z_{n-1}) p_U(y_n - z_n, |y_{n-1} - z_{n-1}) b(z^{(n-1)}|y^{(n-1)})}{p_Y(Y_n|y^{(n-1)})}.
\]

After conditioning on $Y^{(n)}$ and also on survival to time $n$ (that is, on the event $\tau > n$), we have the conditional density $g_n(\cdot|Y^{(n)})$ of $Z^{(n)}$, given by
\[
g_n(z^{(n)}|y^{(n)}) = \frac{b_n(z^{(n)}|y^{(n)})}{\int_{A(n)} b_n(z|y^{(n)}) \, dz},
\]
where the region of integration for the denominator (survival) probability is
\[
A(n) = \{z \in \mathbb{R}^n : z_1 \geq \hat{\gamma}, \ldots, z_n \geq \hat{\gamma}\}.
\]

We do not have an explicit solution for the survival probability, $\int_{A(n)} b_n(z|y^{(n)}) \, dz$, but numerical integration can be done recursively, one dimension at a time, from the explicit recursive solution (33) for $b_n$. Given the joint density $g_n(z^{(n)}|y^{(n)})$ for $Z^{(n)}$, we can integrate with respect to $z^{(n-1)}$ to obtain the marginal density of $z_n$, and from the intensity $^{20}$ of $\tau$ on date $n$, for $n < \tau$.

### 3.3. General Default or Re-Structuring Intensity

Our results in Section 2 on default intensity can be significantly extended.

As with Fischer, Heinkel, and Zechner (1989) and Leland (1998) one can consider cases in which the firm will recapitalize when the level of assets reaches

\(^{20}\) In order to compute the intensity, it is of course numerically easier to obtain the derivative of $b_n$ with respect to $z_n$ explicitly, and then to integrate this with respect to $z^{(n-1)}$, reversing the order of differentiation and integration to save one numerical step.
some sufficiently high level \( \bar{v} \). For example, the firm could issue callable debt, giving it the right to pay down for the existing debt at face value. For a given fixed frictional cost for calling the debt, it would be optimal to call when \( V \) hits a sufficiently high level \( \bar{v} \). In order to compute the density \( f \) of \( Z_t \) given a noisy signal \( Y_t \), and neither liquidation nor recapitalization by \( t \), we would simply replace the probability \( \psi(z, x, \sqrt{t}) \) used in (17) with the analogous term based on the probability \( \psi^*(z, y, \bar{v}, \sqrt{t}) \) that a pinned standard Brownian motion starting at \( z \in (0, \bar{v}) \) at time 0, and finishing that time \( t \) at level \( y \), does not leave the interval \( (0, \bar{v}) \) during \( [0, t] \). This probability can be obtained explicitly from results found, for example, in Harrison (1985). As for the intensity, we let \( \tau^* = \inf \{ t : V_t \notin (\underline{v}, \bar{v}) \} \), \( \tau = \inf \{ t \leq \tau^* : V_t \geq \bar{v} \} \), and \( \tau = \inf \{ t \leq \tau^* : V_t \leq \underline{v} \} \). At \( t < \tau^* \), the intensity \( \lambda_t \) of \( \bar{F} \) is given by

\[
(35) \quad \lambda_t = -\frac{1}{2} \sigma^2 f^*(t, \bar{v}), \quad t < \tau.
\]

The \( (\bar{F}) \)-intensity \( \lambda^* \) for \( \tau^* \) is given at \( t < \tau^* \) by \( \lambda + \bar{\lambda} \).

Another useful generalization replaces the constant default-triggering boundary \( \bar{v} \) with a process \( Z_t \) whose value \( Z(t) \) at \( t \) may not be observable. Suppose, for example, that \( Z \) is a Brownian motion (with some drift and volatility parameters). The difference \( Z^* = Z - \bar{Z} \) is then itself a Brownian motion, and \( \tau = \inf \{ t : Z^*_t \leq \underline{\tau} \} \) is a first-passage time that may be treated by the same methodology just developed. An extension of our result by Song (1998) treats multi-dimensional cases, for example for a model in which the difference \( Z^* = Z - \bar{Z} \) is not a one-dimensional diffusion, and the hitting problem therefore must be formulated as that of a two-dimensional process crossing a smooth surface.

Indeed, even if the boundary \( Z \) is a constant in \( t \), but uncertain, we can apply our results to \( Z^* \), defined by \( Z^*_t = Z_t - \bar{Z} \), provided \( Z \) is itself incompletely observed. If \( Z \) is perfectly observed, however, then our theory does not apply, as the conditional density of \( Z^*_t \) is not both zero and smooth at zero.\(^{21}\) Lambrecht and Perraudin (1996) have presented a model of default based on first passage of an observed diffusion for assets to a trigger boundary that is unobserved by certain debtholders, who are each uncertain of the other debtholder’s valuation of the firm in default.

We can also accommodate an underlying asset process \( V \) that need not be a geometric Brownian motion. For example, suppose \( V \) satisfies a stochastic differential equation of the form

\[
dV_t = \mu(V_t, t) \, dt + \sigma(V_t, t) \, dW_t.
\]

Consider, moreover, some general observation scheme, perhaps continual in time as in Kusuoka (1999), for which, at \( t < \tau \) there exists a conditional density

\(^{21}\) For an argument, see our working paper version.
f(t, ·) for V'. We show in Appendix B, under technical conditions on μ, σ, and f, that the intensity process λ for first hitting of V at v is given by

\[ \lambda = \frac{1}{2} \sigma^2 (v', t) f_v(t, v'), \quad t < \tau. \]

**APPENDICES**

**A. Proof of Proposition 2.2**

Let \( Z_t = Z_0 + mt + \sigma W_t \). Without loss of generality, let \( \bar{v} = 0 \) and define \( \tau_0 = \inf \{ s > 0 : Z_s = 0 \} \). To begin with, we consider a fixed time \( t > 0 \). For now, we suppose that the only information available is survivorship; that is, \( \mathcal{F}_t \) is generated by \( \{ \mathcal{F}_{s \wedge \tau_0} : s \leq t \} \). On the event \( \mathcal{F}_t \), it follows directly from results in Harrison (1985) that \( Z_t \) has a conditional density \( f(t, ·) \), denoted \( f' \) for notational simplicity. This density is bounded, satisfies \( f(0) = 0 \), and has a bounded derivative, with \( f'(0) \) defined from the right. We let

\[ \bar{\lambda} = \lim_{h \to 0} \frac{1}{h} \int_{(t, \infty)} \pi(h, x, m, \sigma) f(x) dx, \]

where \( \pi(h, x, m, \sigma) \) denotes the probability of first passage to zero before time \( h \) for an \( (m, \sigma) \)-Brownian motion with initial condition \( x \). Our first objective is to show that this limit exists and that

\[ \bar{\lambda} = \frac{1}{2} \sigma^2 f'(0). \]

From expression (11) on page 14 of Harrison (1985) (noting that the probability of hitting 0 before \( h \) starting from \( x > 0 \) with drift \( m \) is the probability of hitting the level \( x \) starting from 0 before \( h \) with drift \( -m \)), we have, by substituting \( z = x/(\sigma \sqrt{h}) \),

\[ \bar{\lambda} = \lim_{h \to 0} \frac{1}{h} \int_{(0, \infty)} \left( 1 - \phi \left( \frac{x + mh}{\sigma \sqrt{h}} \right) + \exp \left( -\frac{2mx}{\sigma^2} \right) \phi \left( \frac{-x + mh}{\sigma \sqrt{h}} \right) \right) \times f(x) dx \]

\[ = \lim_{h \to 0} \int_{(0, \infty)} \left( 1 - \phi \left( \frac{m \sqrt{h} z}{\sigma} \right) + \exp \left( -\frac{2m \sqrt{h} z}{\sigma} \right) \phi \left( -\frac{z + m \sqrt{h}}{\sigma} \right) \right) \times \frac{1}{h} f(\sigma \sqrt{h} z) \sigma \sqrt{h} dz, \]

\[ = \lim_{h \to 0} \int_{(0, \infty)} G_1(z, h)G_2(z, h) dz, \]
where
\[ G_1(z, y) = 1 - \Phi\left(z + \frac{m\sqrt{h}}{\sigma}\right) + \exp\left(-\frac{2m\sqrt{h}}{\sigma}\right) \Phi\left(-z + \frac{m\sqrt{h}}{\sigma}\right) \]
and
\[ G_2(z, h) = \frac{f(\alpha\sqrt{h}z)}{\alpha\sqrt{h}z} \sigma^2. \]

Thus, if the dominated convergence theorem can be applied, we have
\[ (A.2) \quad \bar{\lambda} = \int_{(0, \infty)} G_1(z, 0)G_2(z, 0)z dz \]
\[ = \int_{(0, \infty)} (1 - \Phi(z) + \Phi(-z))f'(0)\sigma^2 z dz \]
\[ = \sigma^2 f'(0) \int_{(0, \infty)} 2\Phi(-z)z dz = \frac{1}{2}\sigma^4 f'(0), \]
as desired. To justify dominated convergence, first note that since the derivative of \( f \) is bounded, there exists a constant \( K \) such that
\[ (A.3) \quad \left| \frac{f(\alpha\sqrt{h}z)}{\alpha\sqrt{h}z} \right| \leq K. \]
Now note that (for \( h < 1 \))
\[ |G_1(z, h)| \leq G(z) = 1 - \Phi\left(z - \frac{|m|}{\sigma}\right) + \exp\left(\frac{2|m|z}{\sigma}\right) \Phi(-z). \]
We use the fact that \( 1 - \Phi(x) \) behaves like \( \phi(x)/x \) as \( x \to \infty \) to see that \( G(z) \) goes to zero exponentially fast as \( z \to 0 \). Hence, we have shown that for \( h < 1 \),
\[ |G_1(z, h)G_2(z, h)z| < K\sigma^2 z G(z), \]
and this provides the integrable upper bound (for all \( h < 1 \)) justifying the application of dominated convergence.

In our model there is perfect information at time \( T_0 \) and we can therefore only establish the existence of an intensity for \( t > 0 \) and we do this by proving existence on compact intervals of the form \([t, T]\) for all \( t > 0 \). Having established (A.1), we need to check (see Aven (1985)) that there exists a positive measurable process \( \gamma \) satisfying for every \( T \)
\[ \int_t^T \gamma(s, \omega) ds < \infty \quad \text{a.s.}, \]
and that dominates the error of approximation in the following sense. For each \( T \), there exists for almost every \( \omega \) an \( n_0 = n(T, \omega) \) such that, for \( n > n_0 \),
\[ |Y_n(s, \omega) - \lambda(s, \omega)| \leq \gamma(s, \omega) \quad \text{for all } s \leq T, \]
where \( Y_n \) is the process defined by
\[ Y_n(s) = \frac{1}{h_n} P(z_0 \leq s + h_n, \mathbb{I}_{(T > s)}), \]
for some fixed sequence \( \{h_n\} \) of positive reals converging to zero. Note that \( n_0 \) can depend on \( \omega \).
We first verify that the process $\lambda$ itself satisfies this integrability condition. Assume $Z_0 = z_0$. Between time $t$ and the first accounting report at time $t_1$, assuming no default, the density of $Z_t$ can be written as $f(t, z_0)$, which does not depend on $\omega$ and has an analytical expression. (See, for example, Harrison (1985).) This density satisfies $f(t, 0, z_0) = 0$ and is differentiable as a function of $(t, x)$, with the derivative $f_x(t, \cdot, z_0)$ bounded uniformly on $[t, t_1]$ as can easily be seen by including $t_1$ in the domain. The density at the first accounting report is derived in Section 2.3 as $g(x) = Y(t_1, \omega, z_0, t_1)$, which for each given outcome $Y(t_1, \omega)$ is zero for $x = 0$ and has a bounded derivative with respect to $x$. If we let $s$ be a given time after the first accounting report but before the next, the density of $Z_{s+}$ is given by

$$\int_0^\infty f(s, x, u)g(u|Y(t_1, \omega), z_0, t_1) \, du.$$ 

The derivative with respect to $x$ can be taken inside the integral, so the derivative of the density at time $t + s$ with respect to the point $x$ is

$$f_x(t_1 + s, x, \omega) = \int_0^\infty \frac{d}{dx} f(s, x, u)g(u|Y(t_1, \omega), z_0, t_1) \, du.$$ 

We see from these two expressions that the density inherits from $\tilde{f}$ the properties of being 0 at $x = 0$ and having a uniformly bounded derivative with respect to $x$ over the finite interval $[t_1, t_2]$. Since there are only finitely many accounting reports over a finite period of time, it follows that the bound of the derivative can be obtained by taking the maximum of the bounds needed for each interval between accounting reports. This proves integrability of a sample path of $\lambda$ by proving the stronger property that for each $x$, $f_x(t, \cdot, \omega)$ is bounded as a function of $x$, with one bound holding uniformly over $[t, T]$.

It now follows from the triangle inequality that we only need to verify that for each $t$, there exists for almost every $\omega$ an $n_0 = n(t, \omega)$ such that

$$\int_t^\infty |Y_s(s, \omega)| ds < \infty, \quad n > n_0.$$ 

To see this, we first note that, by the strong Markov property of $Z$, on the event $\{r > t\}$,

$$P(\tau_0 \leq h_0 + t|Z(t)) = \pi(h_0, Z(t), m, \sigma).$$ 

Because $\pi(h_0, \sqrt{h_0} z, m, \sigma)$ declines exponentially fast in $z$,

$$|Y_s(s, \omega)| = \int_0^\infty \pi(h_0, \sqrt{h_0} z, m, \sigma) \left| \frac{f(s, \sqrt{h_0} z, \omega)}{\sqrt{h_0} z} \right| dz$$

is bounded, using the fact shown above that, for almost every $\omega$ (and $n$ such that $h_0 < 1$), the derivative $f_x(s, x, \omega)$ is bounded uniformly in $s$. Hence $|Y_s(s, \omega)| < \infty$ whenever $n_0$ is chosen so that $h_0 < 1$ for $n > n_0$. This concludes the proof.

**B. General Diffusion Results**

We now provide results regarding the default intensity and conditional density for cases in which the asset process $V$ solves a stochastic differential equation of the form

$$dV_t = \mu(V_t, t) \, dt + \sigma(V_t, t) \, dW_t.$$  

We use the fact that there are no exact accounting reports after $t$. At such times the intensity would not exist, just as it does not exist at time 0 when $Z_0$ is known. To have exact reports but still maintain an intensity, one could introduce random report times, where the report times themselves have an intensity process.

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**Note:** The text appears to be self-contained with no external references or citations, which might indicate it is part of a larger context or document. The provided blocks are fragments of a larger discussion on financial mathematics, likely related to credit default modeling. Each section seems to build upon the previous, with a focus on the properties and conditions of a process $Z_t$ and its derivatives. The text includes mathematical expressions and conclusions aimed at proving integrability and boundedness of certain functions over specific intervals.
Without loss of generality we study the first hitting time of the level 0 starting from an unknown positive level. We will use the following regularity for the coefficient functions $\mu$ and $\sigma$.

**Condition A**

A.1. The coefficients $\mu$ and $\sigma$ satisfy global Lipschitz and linear growth conditions, in that there exists a fixed constant $K$ such that, for any $x$, $y$, and $t$,

$$(B.2) \quad |\mu(x,t) - \mu(y,t)| + |\sigma(x,t) - \sigma(y,t)| \leq K|x-y|,$$

and

$$(B.3) \quad \mu(x,t)^2 + \sigma(x,t)^2 \leq K^2(1 + x^2).$$

A.2. There exists constants $l$ and $r$, with $-\infty \leq l < 0 < r \leq \infty$, such that $\sigma(t, \cdot)$ is bounded away from 0 on every compact subset of $(l, r)$, uniformly in $t$, and such that $P(V_t \in (l, r) \text{ for all } t) = 1$.

A.3. $\sigma(t, \cdot)$ is $C^1$ on $(l, r) \times [0, \infty)$.

Condition (A1) is standard, ensuring that a unique, strong solution to the SDE exists. (A2) allows for cases (such as geometric Brownian Motion less a constant) in which the diffusion lives in an open (proper) subset of $\mathbb{R}$, containing the boundary, and the volatility function is positive on this subset. (A3) facilitates the proof, but can be relaxed. We consider a case with no instances of perfect information and assume that for every $t \geq 0$, $V_t$ admits a regular conditional distribution function $F(\cdot | \mathcal{F}_t)$ given $\mathcal{F}_t$. That is:

(i) for each $x > 0$, $F(x | \mathcal{F}_t)$ is a version of $P(V_t < x | \mathcal{F}_t)$;

(ii) for every $\omega$, $F(\cdot | \mathcal{F}_t)(\omega)$ is a distribution function.

On $(\omega, t)$ for which $\tau(\omega) > t$, we assume that $F(\cdot | \mathcal{F}_t)$ has a density denoted $f(t, \cdot, \omega)$ (or sometimes simply “$f(t, \cdot)$,” notationally suppressing dependence on $\omega$). Whenever $\tau(\omega) \leq t$, we arbitrarily set $f(t, t, \omega) = 0$. Condition B forms technical assumptions regarding this conditional density.

**Condition B**

B.1. For each $(\omega, t)$, we have $f(t, 0, \omega) = 0$ and $f(t, \cdot, \omega)$ is continuously differentiable on $(0, \infty)$ and differentiable from the right at $x = 0$. Furthermore, for almost every $\omega$, $|f_x(s, x, \omega)|$ is bounded on sets of the form $\{(s, x): 0 \leq s \leq t, 0 \leq x < \infty\}$.

B.2. For each fixed $x > 0$, the process $\{f_x(t, x): t \geq 0\}$ is $(\mathcal{F}_t)$-progressively measurable.

We have seen that Condition B holds in our basic model. Smoothness of $f$ also holds for more general diffusions under purely technical smoothness conditions on the drift coefficients $\mu$ and the volatility $\sigma$, with a filtration $(\mathcal{F}_t)$ defined by “noisy observation,” as shown below.

The general result is as follows.

**Proposition B.1:** Let $V$ be given by (B.1), with $\mu$ and $\sigma$ satisfying Condition A. Suppose, for $t < \tau = \inf \{ t: V_t \leq 0 \}$, that the distribution of $V_t$ given $\mathcal{F}_t$ has a density $f(t, \cdot, \omega)$, where $f: [0, \infty) \times \mathbb{R} \times \Omega \rightarrow [0, \infty)$ satisfies Condition B. Let $\lambda(t) = 0$ for $t > \tau$ and let

$$(B.4) \quad \lambda(t, \omega) = \frac{1}{2} \sigma^2(0, t)f_x(t, 0, \omega), \quad 0 \leq t \leq \tau.$$

Then $\lambda$ is an $\mathcal{F}$-intensity process of $\tau$.

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While there may exist other $(\mathcal{F})$-intensity processes for $\tau$, they are equivalent for our purposes. For the sense in which uniqueness applies, see Brémaud (1981, p. 30).
An outline of the proof is as follows: First one shows, by deterministic scaling and time transformation of a Brownian motion, that the limit result (A.1) holds for an Ornstein-Uhlenbeck process, that is, for \( V \) satisfying
\[
dV_t = (a + b V_t) dt + \sigma dW_t.
\]

The fact that the limit does not depend on the drift generalizes to SDEs of the form
\[
(B.5) \quad dY_t = \mu(Y_t, t) dt + \sigma dW_t,
\]
in which \( \mu \) satisfies a linear growth condition, since the solution to the SDE (B.5) can be kept pathwise between two OU processes on a fixed interval, and for these processes we have just seen that the hitting intensity is independent of the drift coefficients. In the general case (B.1), we define the function \( H \) by
\[
H(x, t) = \int_0^x \frac{1}{\sigma(y, t)} dy, \quad x \in (l, r).
\]
Then, with \( Y_t = H(V_t, t) \), we have by Ito’s Formula that
\[
dY_t = \mu_Y(Y_t, t) dt + dW_t,
\]
where \( \mu_Y(Y_t, t) \) can be computed using Ito’s Formula. The first passage time of \( V \) to the level 0 is the same as the first passage time of \( Y \) to the level 0. Our regularity conditions ensure that the drift coefficient \( \mu_Y \) of \( Y \) satisfies Condition A and that the density \( g(\cdot) \) of the initial level of the process \( Y \) satisfies Condition B. Therefore, since \( Y \) has a constant volatility of 1, we know from above that the limit (A.1) when considering \( Y \) hitting 0 is equal to \( g'(0)/2 \), which can be shown to equal \( \frac{1}{2f'(0)} \), proving the limit result for the general case. Given the boundedness condition on \( f' \), the verification of Aven’s condition is analogous to the argument given in Appendix A.

Finally, we show that existence of a smooth conditional state density that is zero on the hitting boundary, as assumed in Condition B, is natural in our setting. We begin with the following result, which conditions only on survival, and follows from Corollary 3.43, page 99, of Cattiaux (1991).

**Proposition B.2:** Suppose \( V \) satisfies \( dV_t = \mu(V_t) dt + \sigma(V_t) dW_t \), where \( \mu: \mathbb{R} \to \mathbb{R} \) and \( \sigma: \mathbb{R} \to \mathbb{R} \) and all of their derivatives exist and are bounded. Suppose, moreover, that \( \sigma(\cdot) \) is bounded away from zero in an open interval \( D \subset \mathbb{R} \), possibly unbounded. Let \( \bar{D} \) denote the closure of \( D \) and \( \tau = \inf\{t: V_t \notin D\} \) denote the time of first exit from \( D \). Then, for any initial condition \( V_0 \) in \( D \) and any time \( t > 0 \), the distribution of \( V_t \) conditional on \( \{\tau > t\} \) has a \( C^\infty \) density on \( \bar{D} \) that is zero on the boundary of \( D \).

Now, for a given \( V_0 \in D \) and time \( t > 0 \), we consider the distribution of \( V_t \) conditional on no exit from \( D \) and some “noisy observations” \( Y_1, \ldots, Y_n \) that may be correlated with the process \( V \). To pick a concrete example that generalizes the case studied in Section 2.2, we suppose that \( Y_i = V(t_i) + U_i \), where \( 0 < t_1 < \cdots < t_i < t \), and where \( U_1, \ldots, U_n \) are independent, and independent of \( V \), and where the distribution of \( U_1 \) has a density that is strictly positive on the real line. We let \( F(\cdot; Y_1, \ldots, Y_n) \) denote the conditional distribution of \( V_t \) given \( \{V_{t_i} \}, Y_1, \ldots, Y_n \).

**Corollary B.3:** On the event \( \tau > t \), \( F(\cdot; Y_1, \ldots, Y_n) \) has, almost surely, a \( C^\infty \) density on \( \bar{D} \) that is zero on the boundary of \( D \).

A proof is provided in the working-paper version of this report, based on Proposition B.2 and Tjur (1974, pp. 260–261), as well as induction in \( n \).

24 For details, see the working-paper version. A new proof of our result is due to Elliott, Jeanblanc, and Yor (1999) and a multivariate extension of our intensity formula (B.4) has been developed by Song (1998).
REFERENCES


